

A comparison of NOAA/AVHRR derived cloud amount with MODIS and surface observation

LIU Jian YANG Xiaofeng and CUI Peng
National Satellite Meteorological Center, CMA, CHINA

outline

- 1. Introduction**
- 2. Data & Methods**
- 3. Validation**
- 4. Conclusion**



1. Introduction

1. ISCCP data

- ▶ 1983-2009
- ▶ $2.5^{\circ} \times 2.5^{\circ}$

2. MOD06 cloud product

- ▶ 2000- now
- ▶ $0.01^{\circ} \times 0.01^{\circ} / 0.05^{\circ} \times 0.05^{\circ}$

3. NOAA / AVHRR data

- ▶ 1989-now
- ▶ $0.01^{\circ} \times 0.01^{\circ}$



2. Data & Methods

Data: NOAA/AVHRR

- ▶ 10°-60°N, 65°-145°E
- ▶ 1989-2008

Method

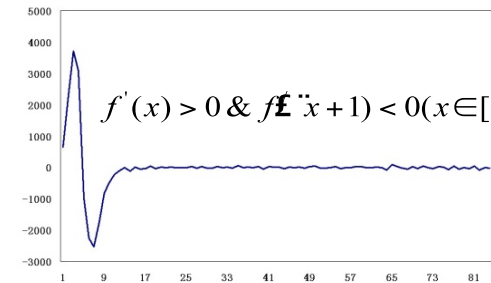
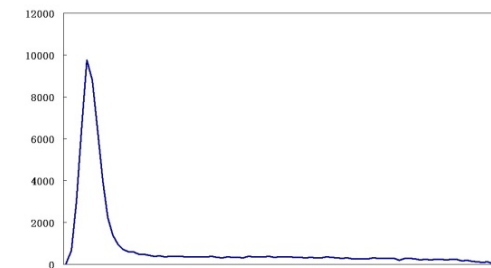
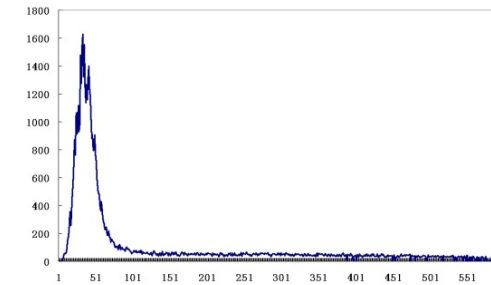
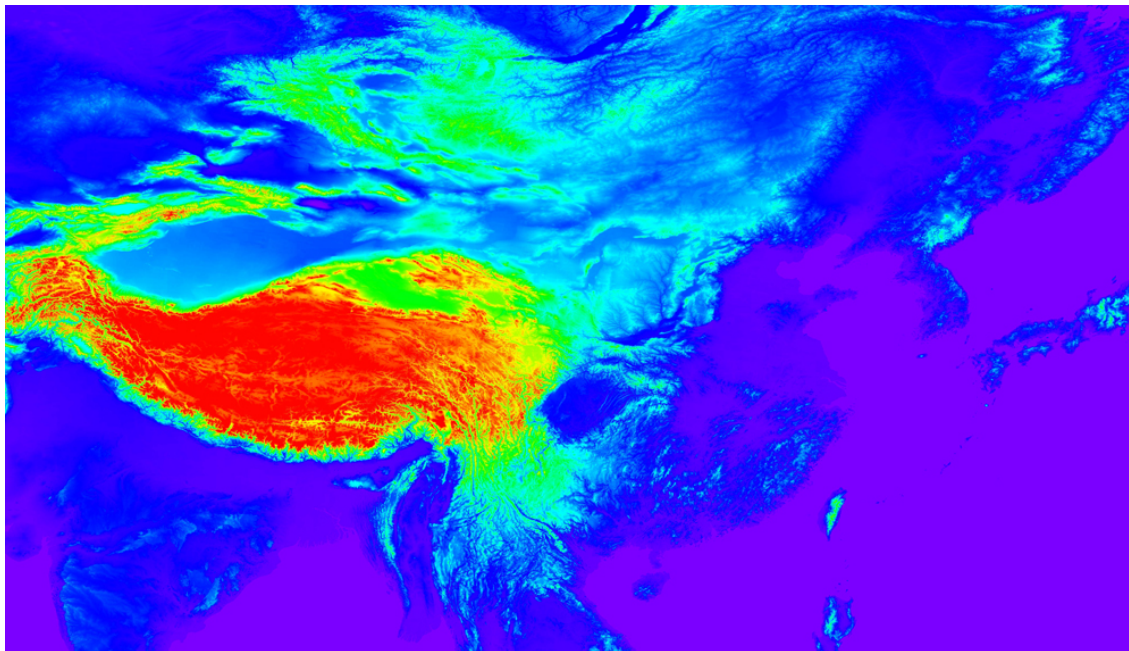
- ▶ Cloud detection
- ▶ Cloud Amount/ cloud fraction



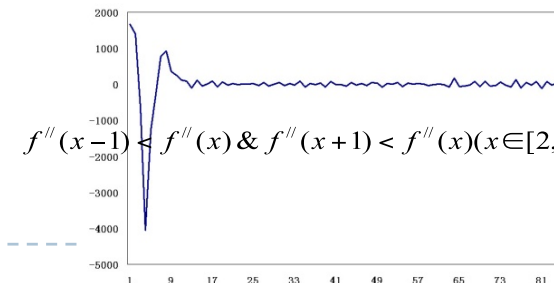
2. Data & Methods

► Cloud detection

- Dynamic threshold
- Background clear fields
- DEM



$$f'(x) > 0 \ \& \ f''(x+1) < 0 (x \in [1, s \max])$$



$$f''(x-1) < f''(x) \ \& \ f''(x+1) < f''(x) (x \in [2, s \max-1])$$



2. Data & Methods

▶ cloud amount

$$I = (1 - A_c)I_{clr} + A_c I_{cld}$$

$$A_c = (I - I_{clr}) / (I_{cld} - I_{clr})$$

$$A_c = (BT - BT_{clr}) / (BT_{cld} - BT_{clr})$$

A_c is pixel's cloud amount.

BT is pixel's brightness temperature at 10.3 μ m channel.

BT_{cld} is brightness temperature of full cloud cover pixel at 10.3 μ m channel.

BT_{clr} is brightness temperature of full clear pixel at 10.3 μ m channel.



2. Data & Methods

▶ Cloud Fraction

 Based on a pixel level cloud detection result

 cloud fraction

$$CF = N_{cloud} / N_{total}$$

N_{cloud} : cloudy pixel number

N_{total} : total pixel number



3. Validation *cloud detection*

▶ *cloud detection*

| | Surface - clear | Surface- cloudy |
|-------------------|-----------------|-----------------|
| Satellite - clear | A | B |
| Satellite- cloudy | C | D |

✚ ACR(the accuracy rate of cloud detection)

$$ACR=(A+D)/(A+B+C+D).$$

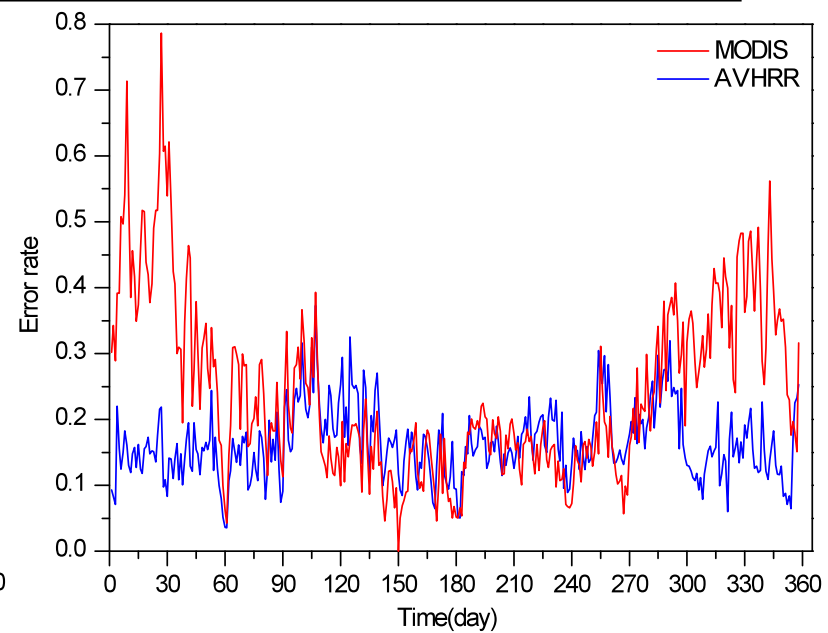
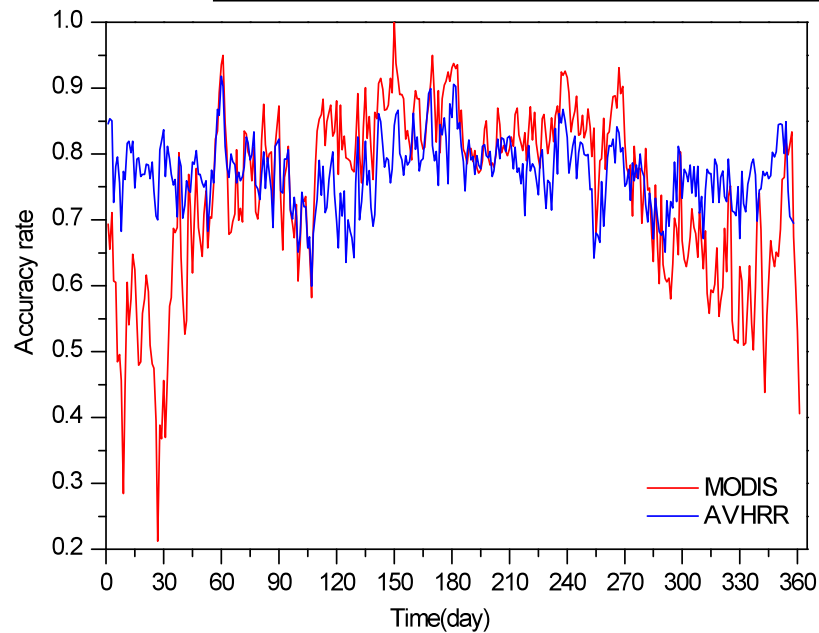
✚ ERR (Error rate)

$$ERR= (B+C) /(A+B+C+D).$$



3. Validation *cloud detection*

| Data | Accuracy Rate | Error Rate |
|--------------|---------------|---------------|
| MODIS | 74.34% | 25.66% |
| AVHRR | 77.12% | 22.88% |

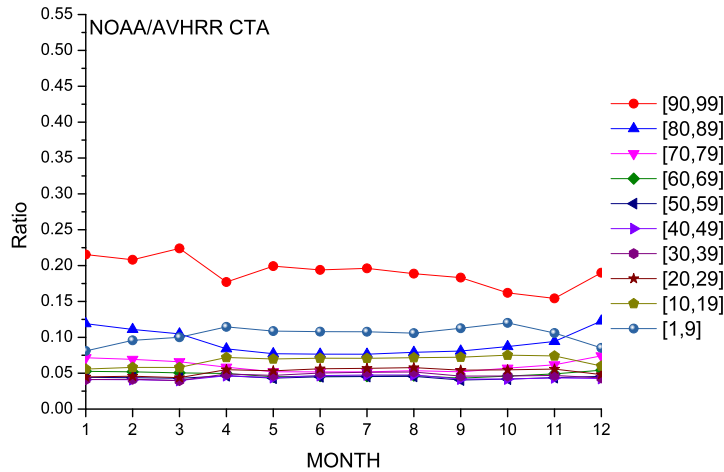


The time series change of the accuracy (left) and error (right) of cloud detection for AVHRR and MODIS

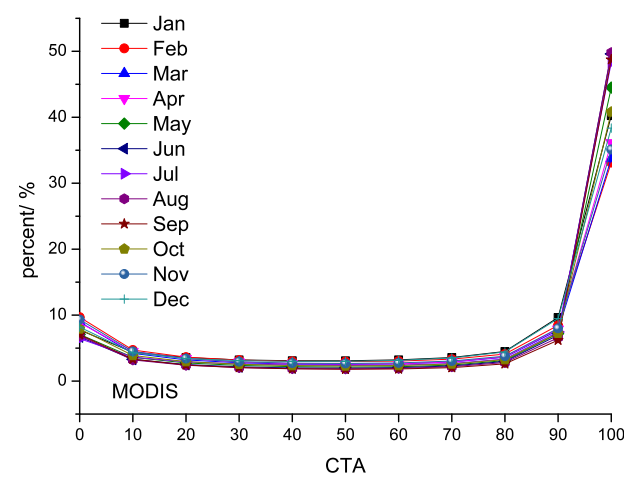
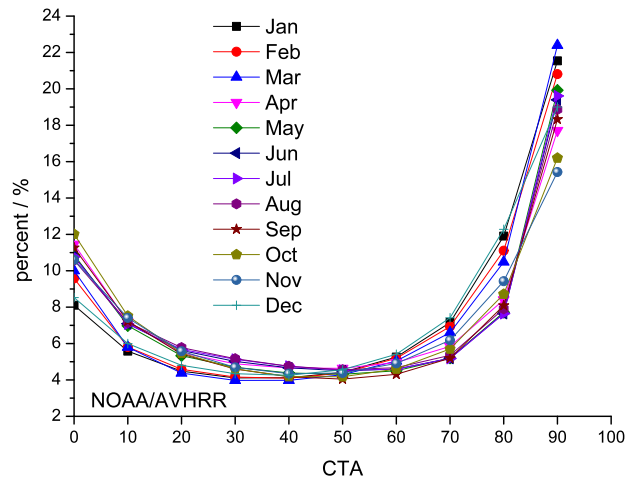
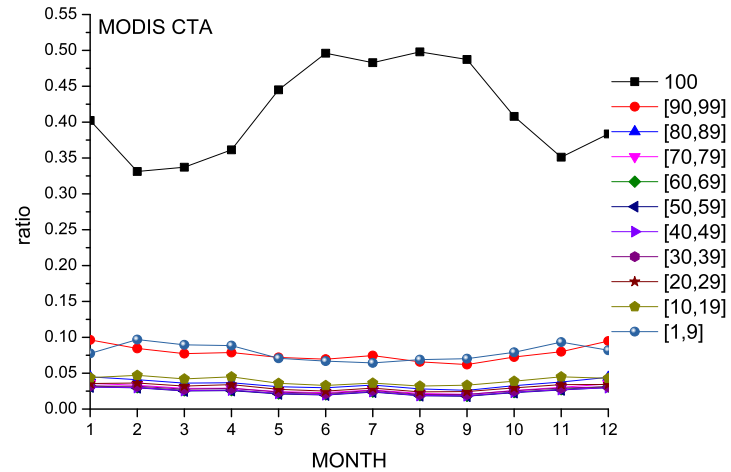


3. Validation_ cloud amount

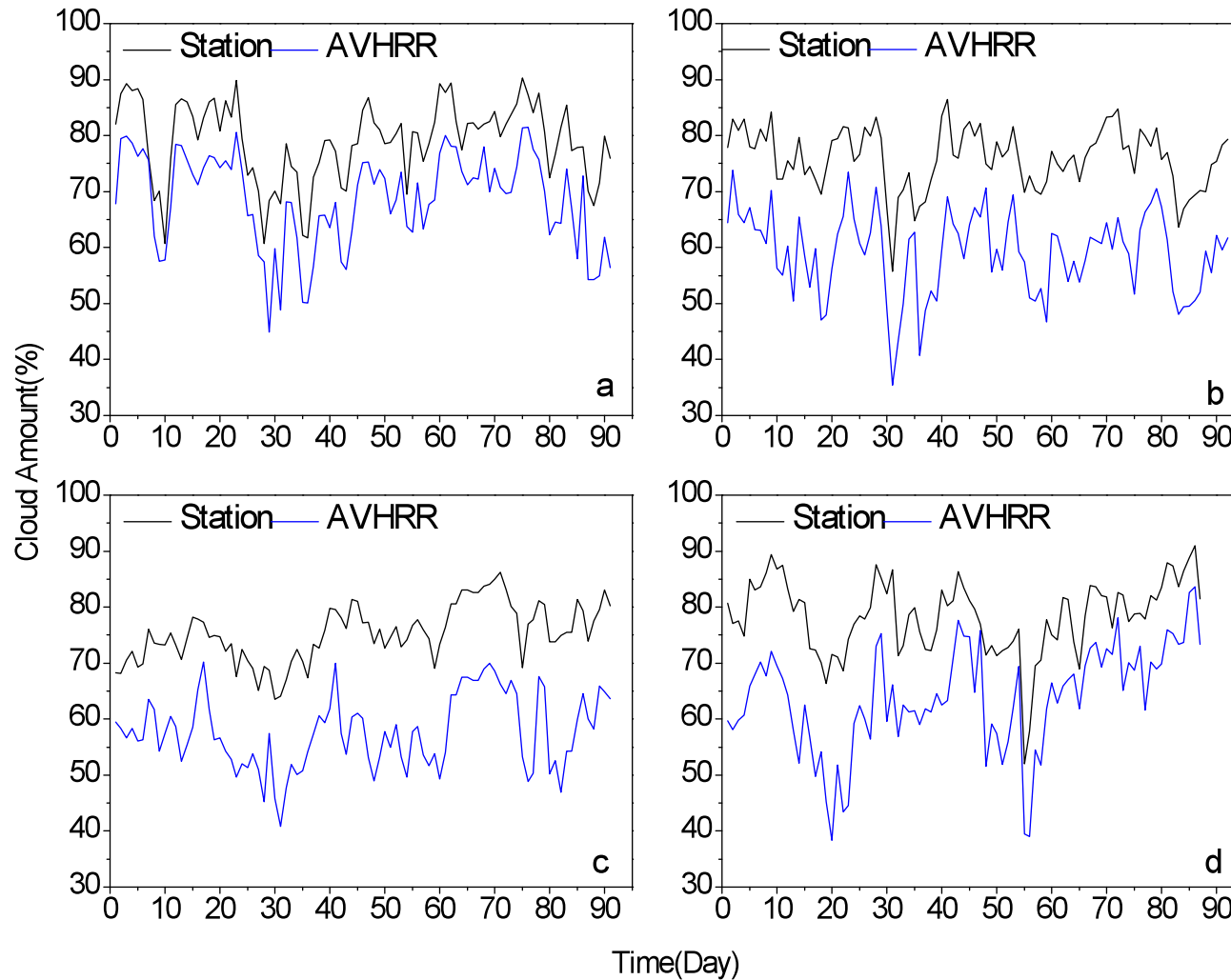
AVHRR



MODIS



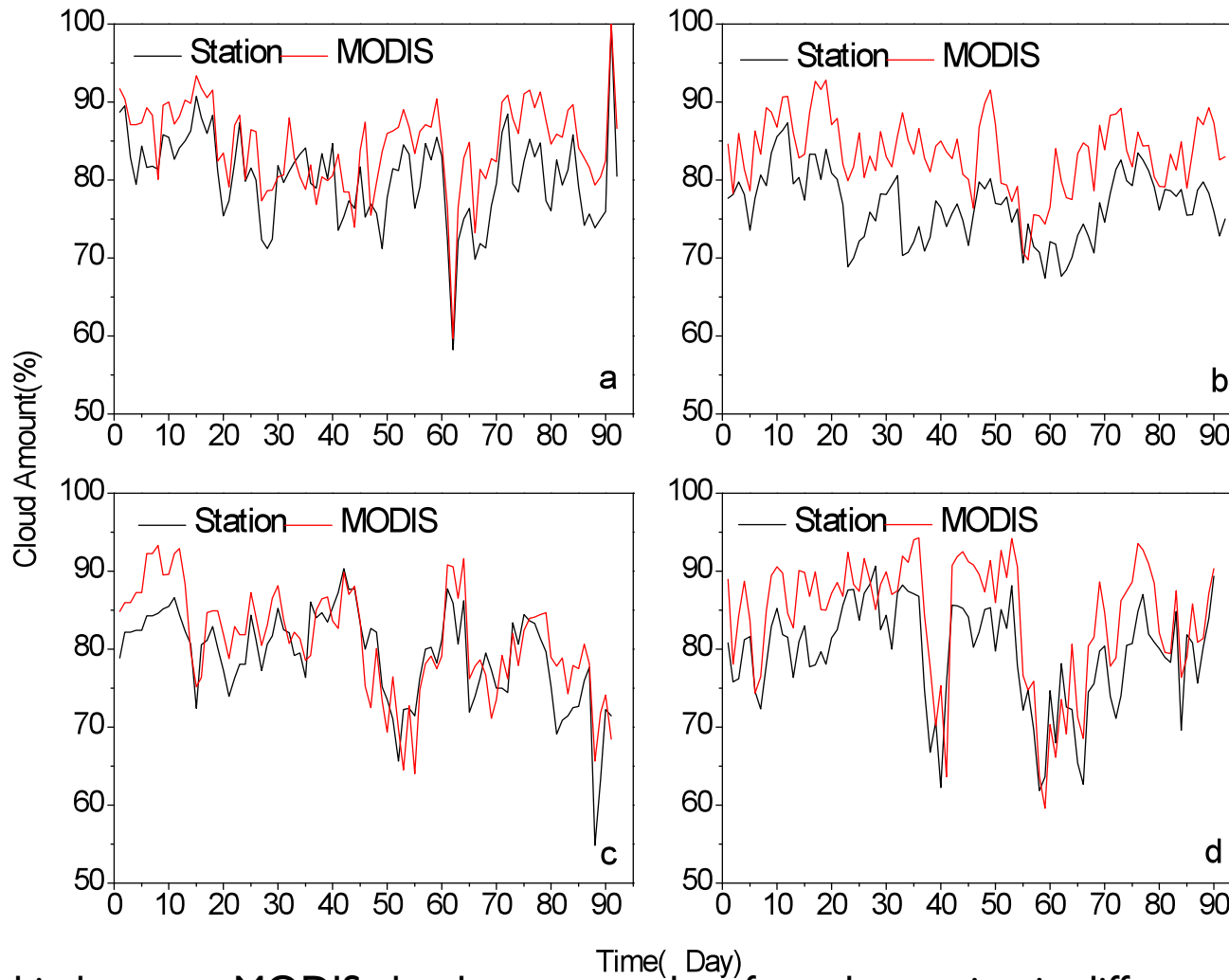
3. Validation_ *cloud amount*



the relationship between AVHRR derived cloud amount and surface observation in different seasons. a spring, b summer c autumn d winter



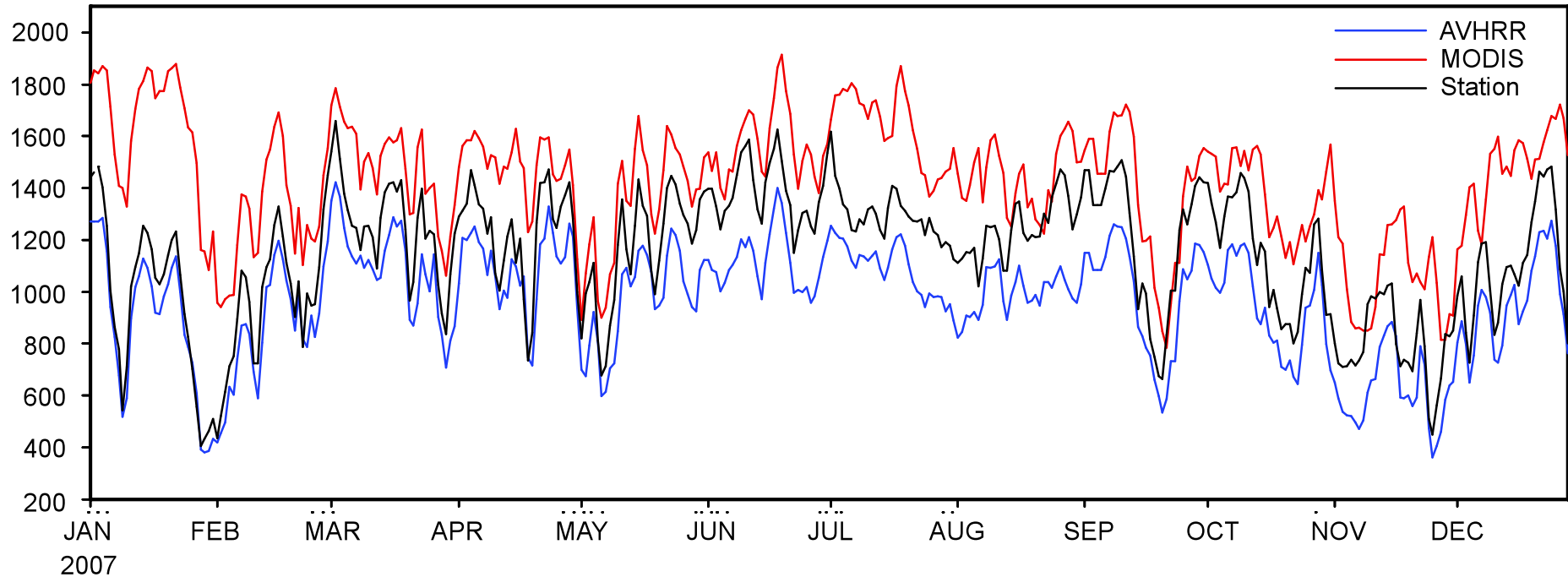
3. Validation_ cloud amount



the relationship between MODIS cloud amount and surface observation in different seasons.a spring, b summer c autumn d winter



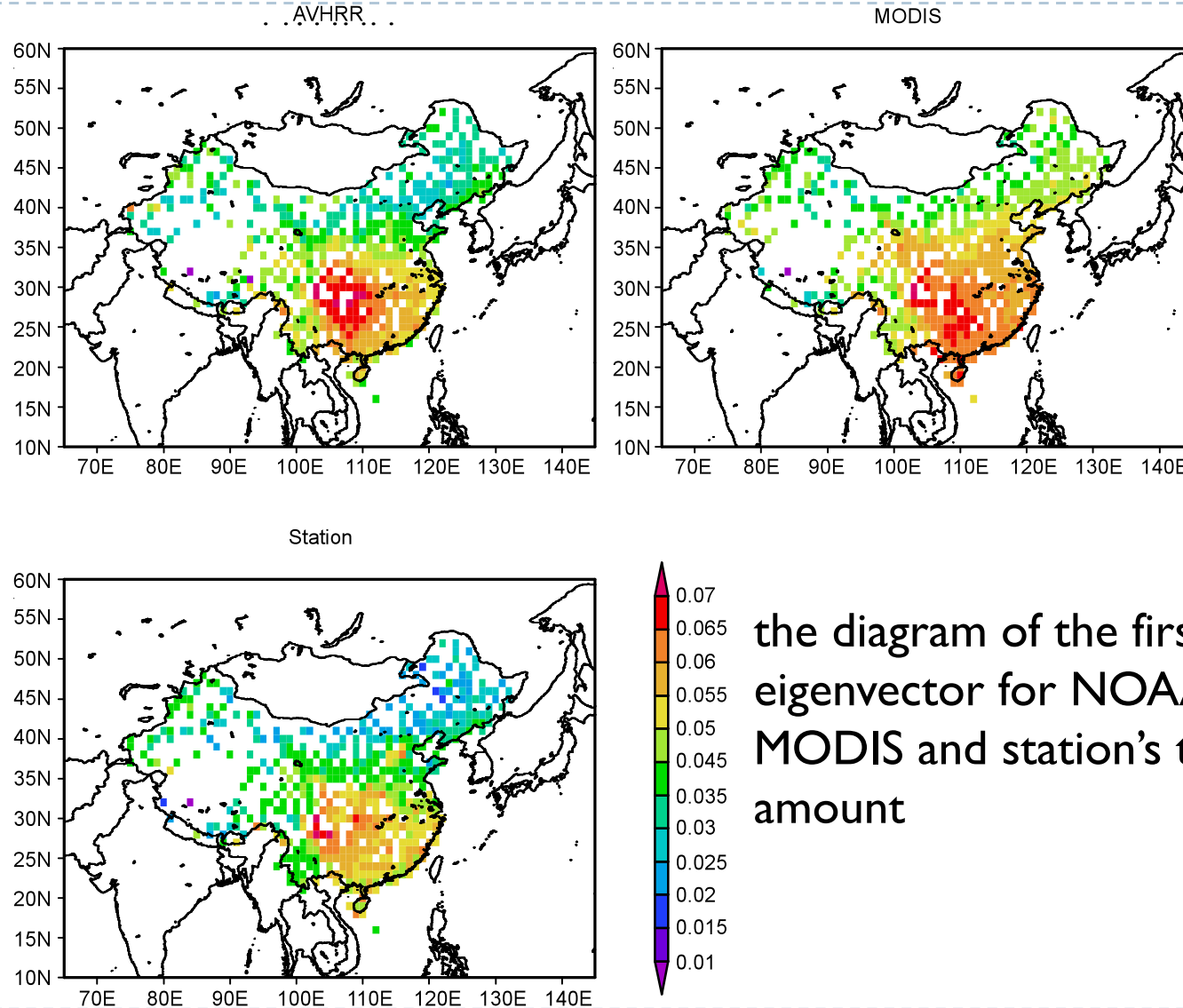
3. Validation_ *cloud amount*



the time coefficient of the first EOF eigenvector for station, AVHRR and MODIS's total cloud amount

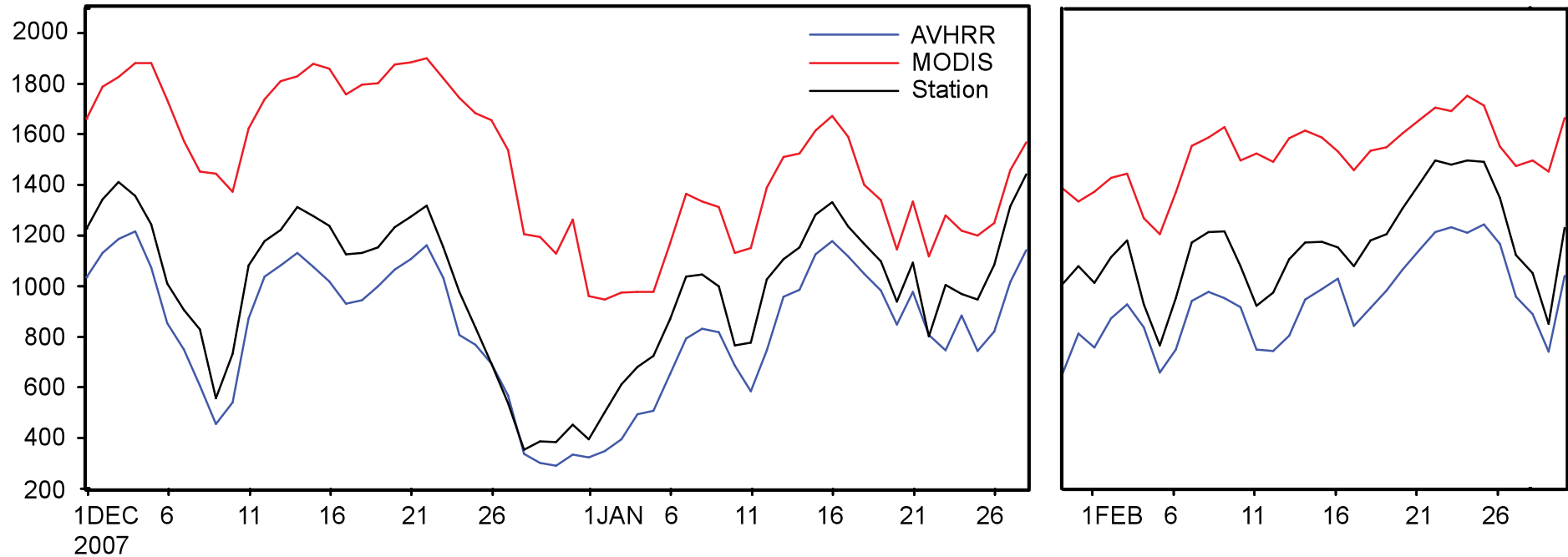


3. Validation_ cloud amount



the diagram of the first EOF eigenvector for NOAA/AVHRR, MODIS and station's total cloud amount

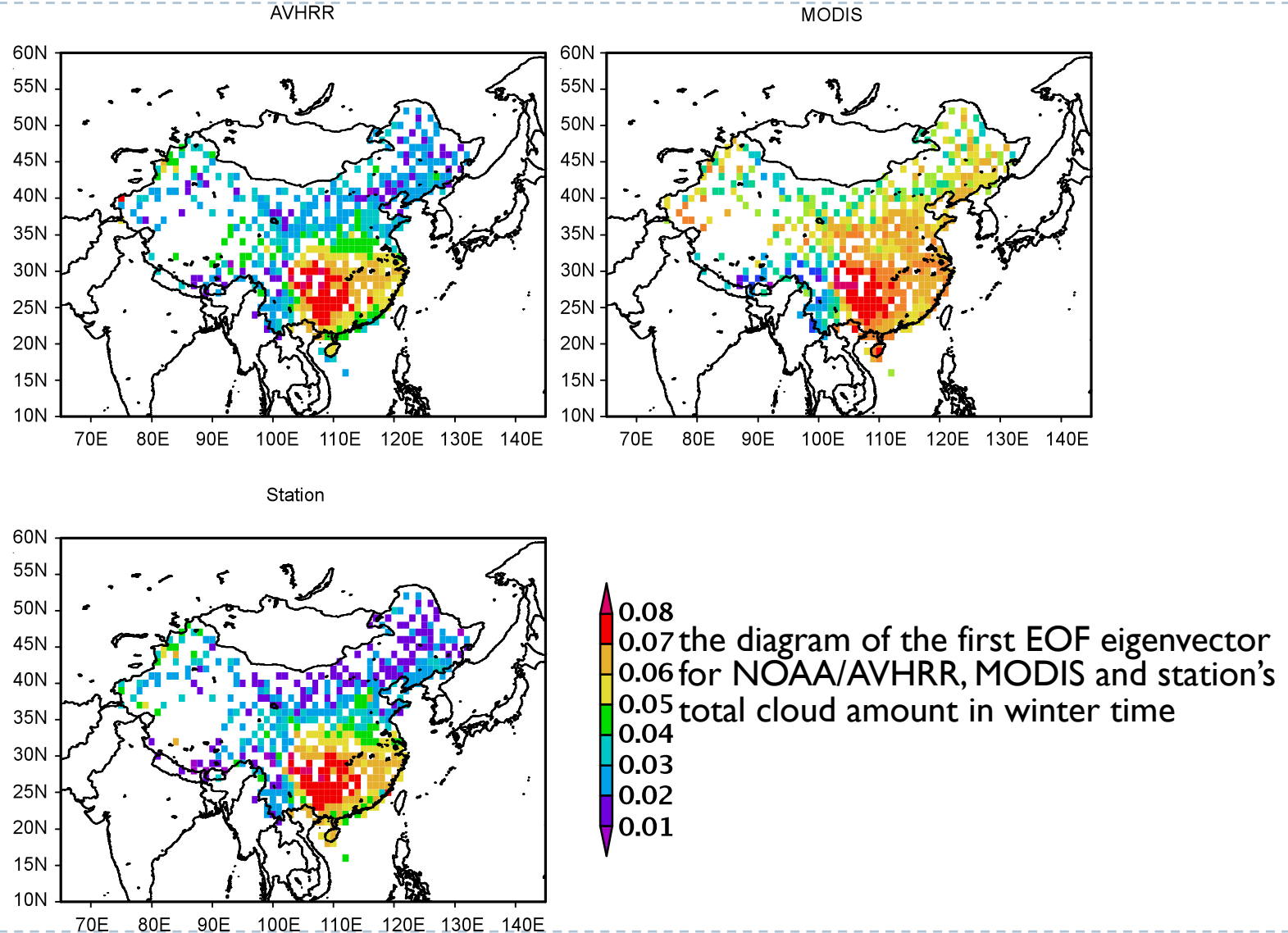
3. Validation_ *cloud amount*



the time coefficient of the first EOF eigenvector for station, AVHRR and MODIS's total cloud amount in winter

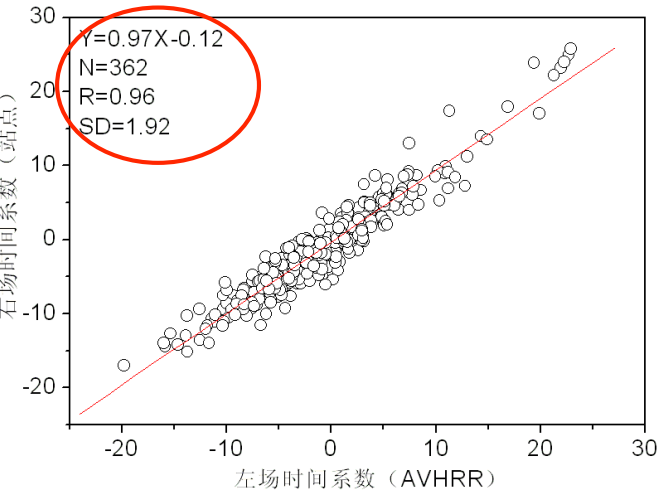
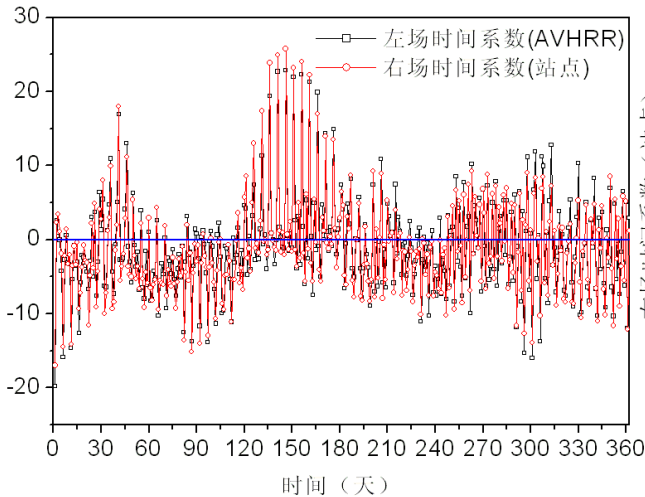


3. Validation_ *cloud amount*

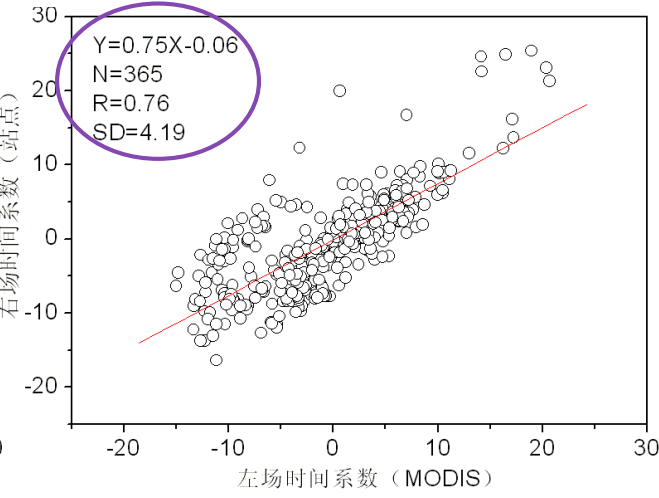
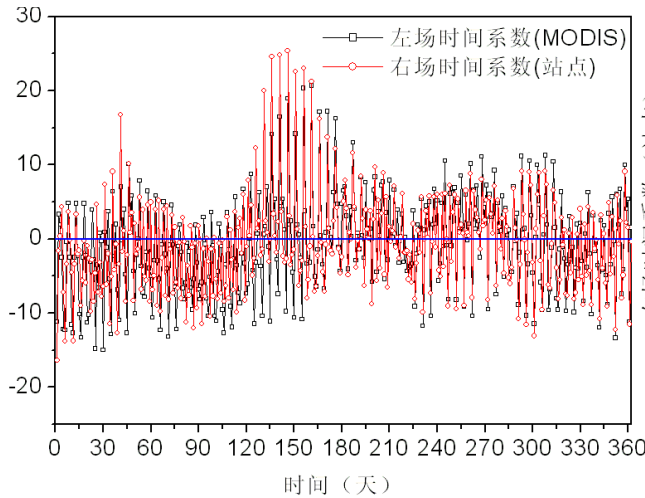


3. Validation_ cloud amount

AVHRR



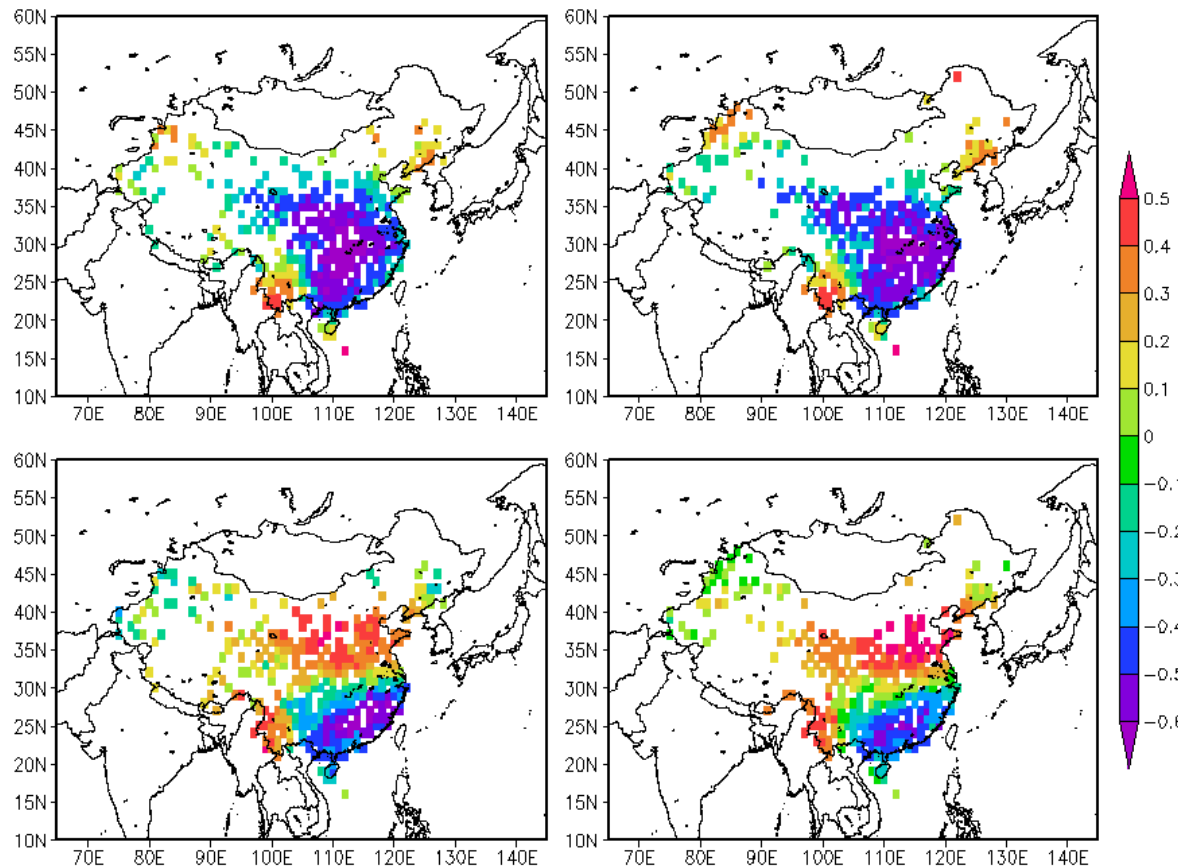
MODIS



the time evolution of SVD time coefficient



3. Validation_ *cloud amount*



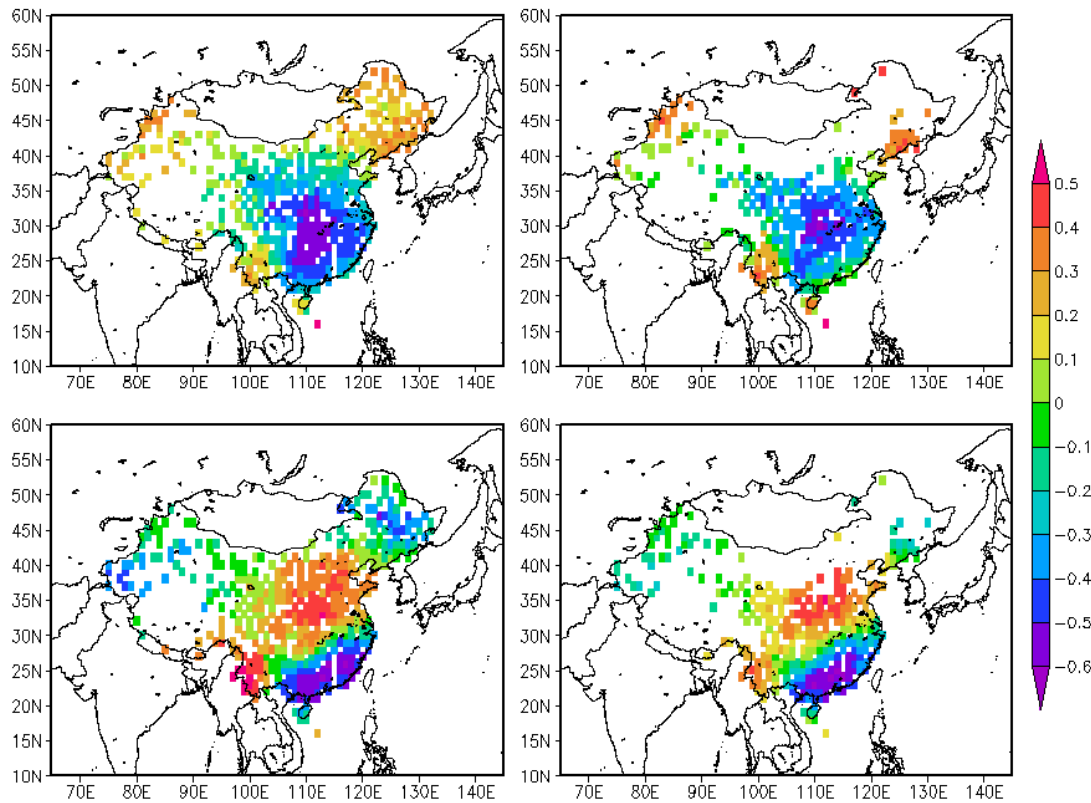
The correlation coefficients

- 1 0.95
- 2 0.95
- 3 0.94
- 4 0.92
- 5 0.88.

SVD heterogeneous correlation map of the first (up) and the second (down) mode, left vector field (AVHRR),right vector field (station observation)



3. Validation_ *cloud amount*



The correlation coefficients

1 0.89

2 0.91

3 0.90

4 0.88

5 0.74.

SVD heterogeneous correlation map of the first (up) and the second (down) left vector field (MODIS),right vector field (station observation)



4. Conclusion

- ▶ The value of AVHRR derived cloud amount is lower than surface observations.
- ▶ Compared with MODIS 74.34% cloud detection accuracy rate, processed AVHRR data get 77.12% cloud detection accuracy rate.
- ▶ update cloud detection algorithm to distinguish cloud and snow and get a good results.



Thanks for
your Attention
