



The UW PEATE Evaluation Capabilities: Resolving Biases Between CALIOP and MODIS Using IR Retrievals for MODIS Collection 6

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Motivation

- The NASA EOS C5 cirrus optical depth retrievals differ by up to a factor of two between observation systems (MODIS (C5), CALIOP (V3), and the CALIPSO IIR)
- When the cirrus OD retrievals are applied to forward radiative transfer calculations, MODIS and CALIOP do not agree with measured TOA radiances
- How do we identify a reference OD and resolve these biases?



Single Layer Ice Clouds



- I Month (January 2010) Non Polar (60 deg)
- Collocated IIR, CALIOP, and MODIS
- Single layer ice clouds less then 4 km thick
- Non attenuating (for CALIOP)
- Ocean only





IR vs MODIS C5 OD







MODIS RGB Jan 11 2010







MODIS C5 Scattering Angle Bias {C5 OD} / {IR OD}







MODIS Scattering Properties

To first order the MODIS retrieval of optical depth is:

$$R_{_v}=(1-g)\times\tau$$

- For ice, g is determined by relating MODIS spectral observations to theoretical single scatter calculations
- Question: Are these calculations representative of real ice crystals?





Effect of Ice Cloud Model Uncertainties On MODIS OD







Effect of Ice Cloud Model Uncertainties On MODIS OD



MODIS Collection 6: severely roughened aggregated column



Collection 5





Collection 6



















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MODIS C6 and CALIOP Modified Lidar ration (25 ->32)



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MODIS L3 Impacts





τ

MODIS L3 Impacts C6





τ





Take away messages

- Both CALIOP and MODIS OP (C5) cirrus retrievals have biases with respect to the IR that are being addressed
- IR optical depth retrievals of cirrus provide a consistent reference (MODIS, CALIPSO IIR)
- Solar reflectance retrievals are very sensitive to model assumptions
- The MODIS C6 OP products will use a modified gamma distribution applied to single habit (severely roughened aggregated columns). The integrated properties and lookup tables will be made available through the MODIS Atmosphere team site (Steve Platnick).
- The CALIOP unconstrained retrieval is using a lidar ratio (too small) that is not consistent with nighttime constrained retrievals. We find that a lidar ratio of 31 results in significantly better agreement with the IR compared to the current value of 25.